

Márton Lőrinc

Lista de lucrări

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[M1] Béla Lantos, **Lőrinc Márton**, *Nonlinear Control of Vehicles and Robots*, Springer, Series: Advances in Industrial Control, 458 pages, 2011, ISBN: 978-1-84996-121-9 (Library WorldCat: 432)

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[M3] **Lőrinc Márton**, Béla Lantos, *Friction Modeling and Adaptive Compensation for Intelligent DC Servo Control*, Intelligent systems in the service of mankind Vol. II, Editor: Wilfried Elmenreich, J. Terreiro Machado and Imre J. Rudas, U Books, Germany, pp. 15-25, 2005, ISBN: 978-3-866-08052-2.

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[RISI-2] **Lőrinc Márton**, Zoltán Szántó, Tamás Haidegger, Péter Galambos, József Kövecses, Internet-based Bilateral Teleoperation Using a Revised Time-Domain Passivity Controller, *Acta Polytechnica Hungarica*, 2017, Vol. 14, No. 8, pp. 27-46.

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